

<b>Subject</b>	Controllers	<b>Course Code</b>	CT320	<b>Theoretical</b>	3hrs / wk
<b>Semester</b>	5	<b>Prerequisite</b>	CT227	<b>Practical</b>	3hrs / wk

### Program Learning Component

<b>Week 1</b>	<b>12. Use of analog controllers in a feedback control system</b>		
	<b>Specific Learning Outcomes</b>	<b>Resources</b>	<b>Practical</b>
	<ul style="list-style-type: none"> <li>• Introduction to controllers systems</li> <li>• Operational amplifier circuits</li> <li>• The Response in Time Domain and Frequency Domain specifications</li> </ul>	Power point slides whiteboard	<ul style="list-style-type: none"> <li>• The selection of the electronic circuit components to apply analog control systems</li> <li>• (simulation by electronic workbench</li> <li>• And implementation in test board</li> </ul>
<b>Week 2</b>	<b>13. Study the proportional controller (design ,simulation and implementation)</b>		
	<b>Specific Learning Outcomes</b>	<b>Resources</b>	<b>Practical</b>
	<ul style="list-style-type: none"> <li>• Proportional controllers</li> <li>• The characteristics of proportional controller</li> <li>• Design proportional controllers</li> <li>• Advantages of proportional controllers</li> <li>• The electronic circuit of the P controller</li> </ul>	Power point slides whiteboard	<ul style="list-style-type: none"> <li>• Applying analog P controller to real process in the Lab</li> <li>• Such as (speed control, level control, flow control, temperature control,etc)</li> </ul>
<b>Week 3</b>	<b>14. Study the proportional plus integral controller (design ,simulation and implementation)</b>		
	<b>Specific Learning Outcomes</b>	<b>Resources</b>	<b>Practical</b>
	<ul style="list-style-type: none"> <li>• Proportional plus integral controllers</li> <li>• The characteristics of roportional plus integration block</li> <li>• Design proportional plus integration block</li> <li>• Advantages proportional plus integration block</li> </ul>	Power point slides whiteboard	<ul style="list-style-type: none"> <li>• Applying analog PI controller to real process in a closed loop control system in the Lab</li> <li>• Such as (speed control, level control, flow</li> </ul>

	<ul style="list-style-type: none"> <li>• The electronic circuit of the PI controller</li> </ul>		control and temperature control,etc)
<b>Week 4</b>	<b>15. Study the proportional plus derivative controller (design ,simulation and implementation)</b>		
	<b>Specific Learning Outcomes</b>	<b>Resources</b>	<b>Practical</b>
	<ul style="list-style-type: none"> <li>• Proportional plus derivative block</li> <li>• The characteristics of proportional plus derivative block</li> <li>• Design proportional plus derivative block</li> <li>• Advantages proportional plus derivative block</li> <li>• The electronic circuit of the PD controller</li> </ul>	Power point slides whiteboard	<ul style="list-style-type: none"> <li>• Applying analog PD controller to real process in a closed loop control system in the Lab</li> <li>• Such as (speed control, level control, flow control, temperature control,etc)</li> </ul>
<b>Week 5</b>	<b>16. Study the proportional plus integral plus derivative controller (design ,simulation and implementation)</b>		
	<b>Specific Learning Outcomes</b>	<b>Resources</b>	<b>Practical</b>
	<ul style="list-style-type: none"> <li>• Proportional plus derivative plus integral</li> <li>• The characteristics of proportional plus integral plus derivative block</li> <li>• Design proportional plus integral plus derivative block</li> <li>• Advantages proportional plus integral plus derivative block</li> <li>• The electronic circuit of the PID controller</li> </ul>	Power point slides whiteboard	<ul style="list-style-type: none"> <li>• Applying analog PID controller to real process in closed loop control systems in the Lab</li> <li>• Such as (speed control, level control, flow control, temperature control,etc)</li> </ul>
<b>Week 6-7</b>	<b>17. Study the digital control systems</b>		
	<b>Specific Learning Outcomes</b>	<b>Resources</b>	<b>Practical</b>
	<ul style="list-style-type: none"> <li>• Introduction to the Digital control systems</li> <li>• (Principles of Digital Control, Theory of Z-Transform and Principles of Z-Transform }.</li> <li>• Stability and analysis of digital control systems</li> <li>• Obtaining the difference equation of</li> </ul>	Power point slides whiteboard	<ul style="list-style-type: none"> <li>• Simulation ,analysis and design of digital control Systems using MATLAB.</li> </ul>

	digital control system • Selection of the sample time		
Week 8-9	<b>18. Study the digital PID controller design, simulation and implementation</b>		
	<b>Specific Learning Outcomes</b>	<b>Resources</b>	<b>Practical</b>
	• Digital PID controller (design ,simulation and implementation )	Power point slides whiteboard	• Applying digital PID controller to a real process in the Lab • Such as (speed control, level control, flow control, temperature control,etc)
Week 10	<b>19. Study the state space representation of dynamic control systems</b>		
	<b>Specific Learning Outcomes</b>	<b>Resources</b>	<b>Practical</b>
	• Control system representation in state space model and it's digital • form	Power point slides whiteboard	• Design and simulation of state feedback control system by Matlab.
Week 11	<b>20. Study how to design and simulate state feedback control system</b>		
	<b>Specific Learning Outcomes</b>	<b>Resources</b>	<b>Practical</b>
	• Controllability check of digital control systems and the design method of state feedback control system	Power point slides whiteboard	• Design and simulation of state feedback control system by Matlab.
Week 12	<b>21.Study how design and simulate state estimator</b>		
	<b>Specific Learning Outcomes</b>	<b>Resources</b>	<b>Practical</b>
	• Observability check of digital control systems and the design method of state estimator	Power point slides whiteboard	• Design and simulation of state estimator control system by Matlab.
Week 13-14	<b>22.Study the cascade control theory and application</b>		
	<b>Specific Learning Outcomes</b>	<b>Resources</b>	<b>Practical</b>
	• Principles and application of the Cascade control systems	Power point slides whiteboard	• Applying different types of controllers to real process as a cascaded control systems in the Lab

			<ul style="list-style-type: none"><li>• (water level and flow control system)</li></ul>
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